

# Solving non-linear Horn clauses using a linear Horn clause solver

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HCVS'16 Eindhoven

03/04/2016

Number of solvers based on Constrained Horn Clauses (CHCs) are available:

After fixing a constraint theory, the (Horn clause) solvers are:

- linear e.g., VeriMap, Sally etc.
- non-linear e.g., RAHFT, SeaHorn, QARMC, ELDARICA, Z3 etc.

since the underlying engine of linear solver can handle only linear clauses which restricts, in principle, their applicability

Can we solve non-linear CHCs using a linear Horn clause solver?

**Notation:** solver = Horn clause solver, linear solver = Horn clause solver for linear Horn clauses

# Is it possible?

Yes, by interleaving **program transformation** (Horn clause linearisation) with **linear Horn solving** in an incremental manner to handle non-linear clauses.

# Example: CHCs defining the Fibonacci function (*Fib*)

```
c1. fib(A, B) :- A >= 0, A <= 1, B = A.  
c2. fib(A, B) :- A > 1, A2 = A - 2, fib(A2, B2),  
    A1 = A - 1, fib(A1, B1), B = B1 + B2.  
c3. false :- A > 5, fib(A, B), B < A.
```

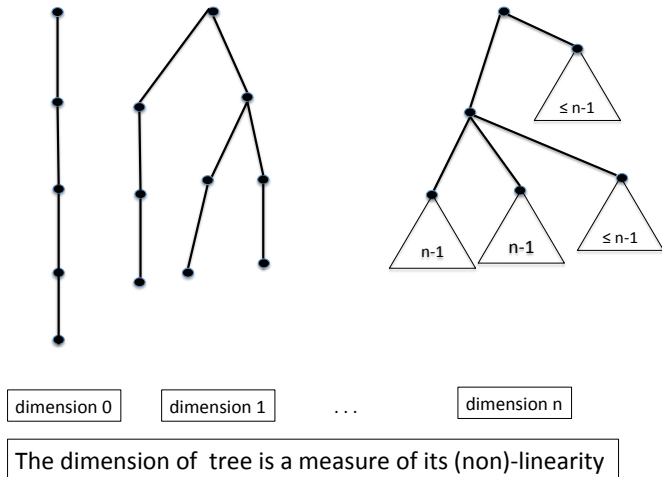
c1 and c3 are linear clauses, c2 non-linear

The Horn clause verification

to show that there is no successful derivation of *false*.

# Program transformation (I)

is based on the idea of **tree dimension** of Horn clause derivations



- Given a set of clauses (program)  $P$ , the notion of *tree dimension* allows us to derive a program  $P^{\leq k}$  ( $P$  at most  $k$  or simply  $k$ -dim program) whose derivations trees have dimension  $\leq k$  ( $k \geq 0$ )

## The Horn clause verification problem based on tree dimension

- show that there is no successful derivation of *false* – of any dimension.
- It is known that  $P^{\leq k}$  is *linearisable* [Afrati et al., 2003].

this allows us to generate programs for increasing value of  $k$ , linearise and solve them.

# Example: dimension bounded program

dimension of Fib's derivation trees depends on the input number.

c1.  $\text{fib}(A, B) :- A \geq 0, A \leq 1, B = A.$

c2.  $\text{fib}(A, B) :- A > 1, A2 = A - 2, \text{fib}(A2, B2),$   
 $A1 = A - 1, \text{fib}(A1, B1), B = B1 + B2.$

c3.  $\text{false} :- A > 5, \text{fib}(A, B), B < A.$

*Fib*<sup>≤0</sup> (linear)

$\text{fib}(0)(A, B) :- A \geq 0, A \leq 1, B = A.$

$\text{false}(0) :- A > 5, B < A, \text{fib}(0)(A, B).$

$\text{false}[0] :- \text{false}(0).$

$\text{fib}[0](A, B) :- \text{fib}(0)(A, B).$

the atom  $p(k)(X)$  means any derivation tree rooted at  $p(0)(X)$  will have tree dimension  $k$

$p[k](X) - \text{tree dimension} \leq k$

# $Fib^{\leq 1}$ (1-linear)

$fib(0)(A,B) :- B=A, A=<1, A>=0.$

$false(0) :- B<A, A>5, fib(0)(A,B).$

$false[0] :- false(0).$

$fib[0](A,B) :- fib(0)(A,B).$

$fib(1)(A,B) :- B=F+D, C=A-2,$   
 $E=A-1, A>1, fib[0](E,F), fib(1)(C,D).$

$fib(1)(A,B) :- B=F+D, C=A-2, E=A-1,$   
 $A>1, fib[0](C,D), fib(1)(E,F).$

$fib(1)(A,B) :- B=F+D, C=A-2, E=A-1,$   
 $A>1, fib(0)(C,D), fib(0)(E,F).$

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All clauses of  $Fib^{\leq 0}$  are in  $Fib^{\leq 1}$



by construction all clauses of  $P^{\leq k}$  are **included** in  $P^{\leq k+1}$  ( $k \geq 0$ )

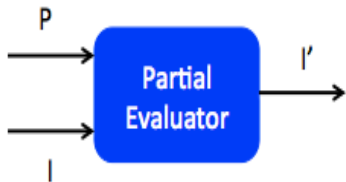
As a result

- it provides a **basis for iterative** strategy for dimension bounded programs.
- **reuse the solution** obtained for lower dimension to linearise/solve clauses of higher dimension

# Linearisation (I)

based on partial evaluation (PE). PE is a source-source program transformation.

- P: non-linear clauses, I: an interpreter (linear in our case, written in some language L (as Horn clauses))
- I' is a specialised interpreter for P, which can be regarded as the transformation of P.



- same as **predicate tupling** (Invited talk).

# Reuse of solution and Linearisation (I)

Assume that the following is the solution for  $Fib^{\leq 0}$

```
fib(0)(A,B) :- B=A, A=<1, A>=0.  
fib[0](A,B) :- B=A, A=<1, A>=0.  
false(0):- FALSE.  
false[0]:- FALSE.
```

Given  $Fib^{\leq 1}$

```
fib(0)(A,B) :- B=A, A=<1, A>=0.  
false(0) :- B<A, A>5, fib(0)(A,B).  
false[0] :- false(0).  
fib[0](A,B) :- fib(0)(A,B).
```

```
fib(1)(A,B) :- B=F+D, C=A-2,  
E=A-1, A>1, fib[0](E,F), fib(1)(C,D).  
fib(1)(A,B) :- B=F+D, C=A-2, E=A-1,  
A>1, fib[0](C,D), fib(1)(E,F).  
fib(1)(A,B) :- B=F+D, C=A-2, E=A-1,  
A>1, fib(0)(C,D), fib(0)(E,F).
```

## *Fib*<sup>≤1</sup> after solution reuse

```
fib(0)(A,B) :- B=A, A=<1, A>=0.
```

```
fib[0](A,B) :- B=A, A=<1, A>=0.
```

```
fib(1)(A,B) :- B=F+D, C=A-2,  
               E=A-1, A>1, fib[0](E,F), fib(1)(C,D).
```

```
fib(1)(A,B) :- B=F+D, C=A-2, E=A-1,  
               A>1, fib[0](C,D), fib(1)(E,F).
```

```
fib(1)(A,B) :- B=F+D, C=A-2, E=A-1,  
               A>1, fib(0)(C,D), fib(0)(E,F).
```

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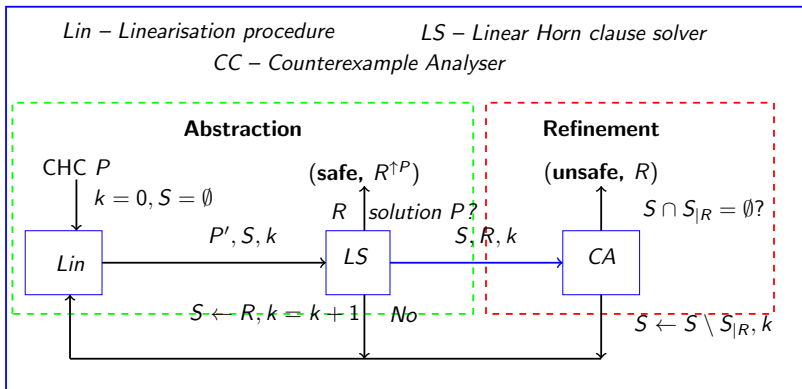
Then we can linearise this program.

# Assumption about a linear solver

- 1 linear solver is a **black box** and is **sound**
- 2 capable of producing a tuple **Status**  $\times$  **Result** where Status  $\in$  {safe or unsafe} and Result  $\in$  {solution, counterexample}

A solution for  $P$  is a set of **constrained facts** of the form:  $p(X) \leftarrow \phi$  for each predicate  $p$  occurring in  $P$

# Our approach



**Figure :** Abstraction-refinement scheme for solving non-linear Horn clauses using a linear solver.  $P'$  is a linearised version of  $P$ 's  $k$ -dim program.  $S|_R$  is a set of constrained facts from  $S$  appearing in a counterexample.

# Example: counterexample using approximate solution

```
c1. false:- X=0, p(X).  
c2. false:- q(X).  
c3. p(X):- X>0.  
c4. q(X):-X=0.
```

Suppose  $S = \{p(X) : \text{TRUE}\}$  for the predicate  $p(X)$ . Using this solution, we get

```
c1. false:- X=0, p(X).  
c2. false:- q(X).  
c3. p(X):- TRUE. (approximate solution)  
c4. q(X):-X=0.
```

$c_1(c_3)$  is a spurious counterexample for the original program

$c_2(c_4)$  is a real counterexample

- 1 Linear solver: **Convex polyhedral analyser (CPA)** – terminates but may generate *false alarms*
- 2 Partial Evaluator: **Logen** [Leuschel et al., 2003]
- 3 Benchmarks: 44 problems (SV-COMP'15, QARMC, Repository of Horn clauses)
- 4 Tool: **LHornSolver**  
(<https://github.com/bishoksan/LHornSolver>)

## Goal

- 1 whether **solving non-linear Horn clauses** can be done using **a solver for linear Horn clauses**?
- 2 the relation between the **solvability** of a program with **tree dimension**
- 3 comparison with tools for non-linear Horn clauses



- 61% of the problems are solved
- we found that the solution of  $P^{\leq k}$  (for  $k = 1, 2$ ) becomes a solution of  $P$  or counterexample was found

The results on this set of benchmarks show that

- it is feasible to solve non-linear Horn clauses using a linear solver and
- the solvability of a problem is shallow wrt. tree dimension of its derivations.

Comparison with RAHFT (whose underlying engine is also CPA), Horn solver for non-linear clauses

- RAHFT solves all the problems unlike LHornSolver

This could mean

- linearisation strategy we use is not useful for solving non-linear Horn clauses
- the use of CPA in LHornSolver: no refinement is done when CPA produces a *false alarm*. In this case LHornSolver returns **unknown**

# What next?

- experiment with **different linearisation strategies** for Horn clause
- **use different linear solver within LHornSolver**, which if returns returns with a solution or a counterexample wrt. the original program

**Thanks for your attention!**